

PN 096-0259-001

English



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**Chapter 1**



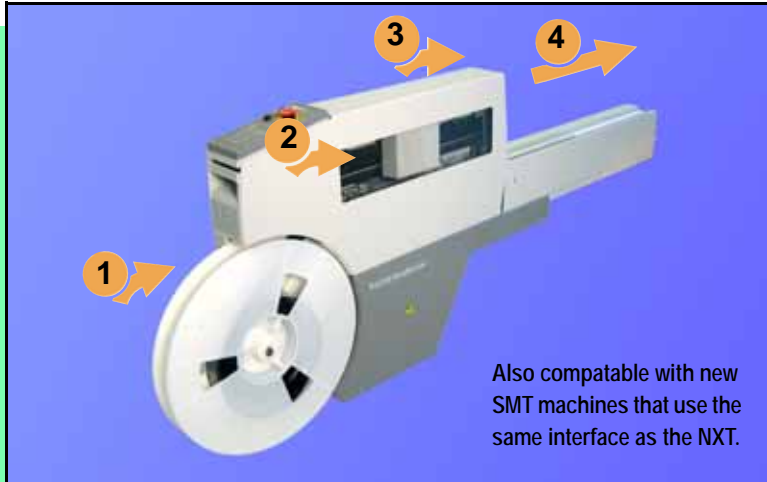
# Overview

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## The ProLINE-RoadRunner for Fuji



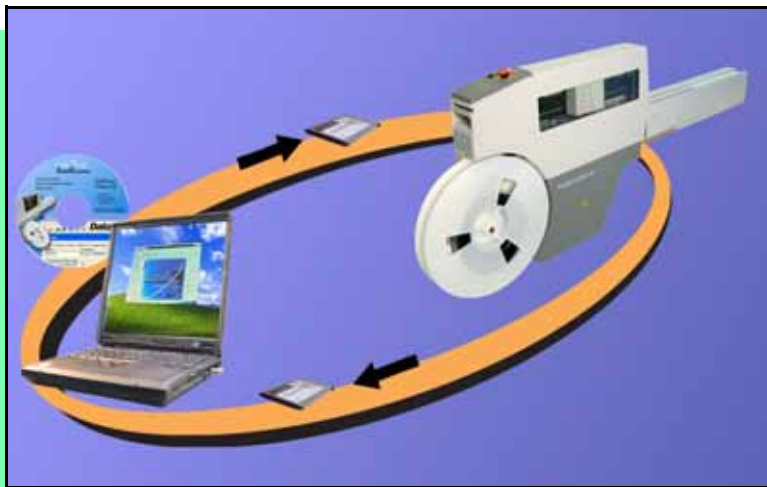
Data I/O is proud to introduce an inline solution for high-volume programming of electronic products.

### ProLINE-RoadRunner:

1. Takes programmable devices from a reel...
2. Places them in sockets and programs them with your data...
3. Places them on a conveyor belt...
4. Delivers them to the pick point of your assembly machine. ■



## Jobs and Statistics



**TaskLink™ for Windows® is required to process devices on ProLINE-RoadRunner.**

**TaskLink allows you to create and manage a job database and it analyzes job statistics.**

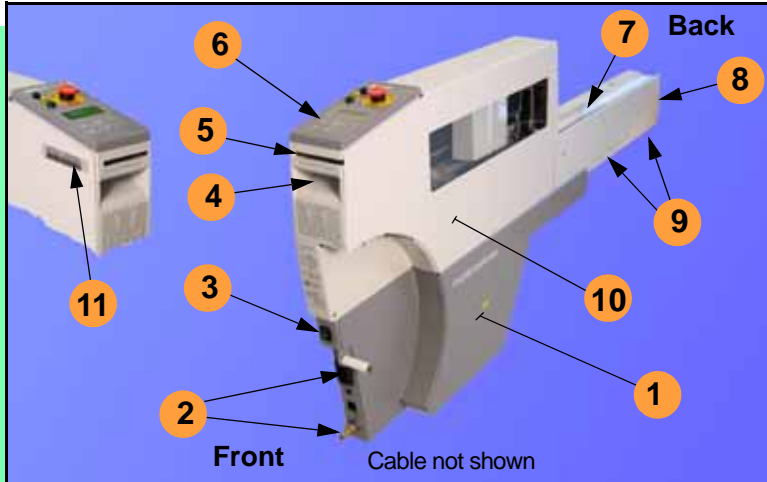
**PCMCIA cards (PC cards) are used to transfer jobs and statistics between TaskLink and RoadRunner.**

**For more information on TaskLink, see the TaskLink Help Menu. ■**





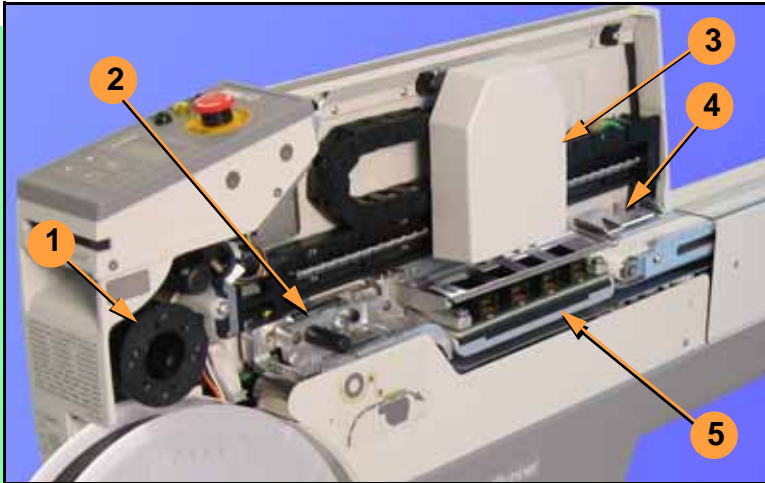
## External Features



1. Electronics Enclosure
2. Power and Air Connections
3. Power Switch
4. Handhold for lifting
5. PC Card Slot
6. Control Panel
7. Conveyor Belt
8. SMT Communications Connection
9. Mechanical Interface to the SMT
10. Robotics Cover
11. Bar Code identification ■



## Internal Components



1. Cover Tape Take-Up Reel
2. Tape-In Module
3. PNP Probes, Precisor, and Head Cover
4. Reject Bin
5. Socket Adapter, Actuator Plate, and Programmer ■





## Control Panel Lights

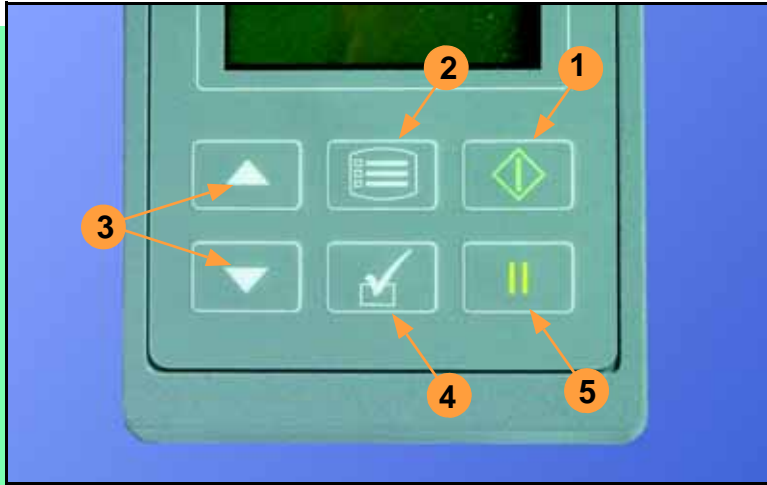


1. **Blue** - Stop Indicator.  
User intervention is required, or the unit is paused.  
(Do not remove the PC card unless blue lamp is lit.)
2. **Yellow** - Caution Indicator.  
Correct a problem or the machine will stop.
3. **Green** - Run Indicator.  
*Lit:* A job is running.  
*Blinking:* Programmed devices are not yet at the SMT pick point.
4. **Emergency Stop** - Press to stop the robot motors in an emergency. To resume motion, rotate the button and press Start. ■





## Control Panel Buttons



1. Start - start or resume the chosen job.
2. Menu - exit to the previous menu, —or show the next message (deleting the current one), —or deselect an item.
3. Up and Down Arrows - scroll through menu items, —or toggle selections, —or advance the device tape.
4. Select - select menu items. In this guide, *Select Job* means to scroll to *Job* and press Select.
5. Pause - interrupt the job without cancelling it. ■





## Operator Menus

| Main Menu      |
|----------------|
| Job            |
| Advance Pocket |
| Align Pocket   |
| Purge          |
| Socket         |

- Light gray shaded fields cannot be changed.
- For *Advance Pocket*, *Align Pocket*, and *Purge*, see Chapter 3 in the Owner's Manual.

| Job     |   |
|---------|---|
| View    | Job Name<br>Device: E28F320<br>Checksum: 3FC00000<br>Mfg: INTEL<br>Adapter: PA-G021<br>Prec: 621-0086-005<br>Act: 644-0016-001  |
| Results | Passed: 992<br>Failed: 4<br>System Yld: 98.7<br>Prgrmr Yld: 99.6<br>Handler Yld: 99.5<br>Parts/Hour: 255<br>MCBI: 201<br>Skt 1 Yld: 99.9<br>Skt 2 Yld: 100<br>Skt 3 Yld: 100<br>Skt 4 Yld: 100<br>Skt Cycles: 249 |

Operator Menus are visible on the Control Panel, and can be navigated by using the Up Arrow and Down Arrow buttons.

Pressing the Menu button displays the next higher menu (one level up). If you are at the main menu, pressing Menu will have no effect. Job is the first item in the main menu.

Operator Menus, Version 05.17.00.C shown, continue on the next page.



## Changing the Pass Limit

| Job continued     |                |
|-------------------|----------------|
| End               |                |
| Remaining Devices | Remaining: 151 |
|                   | +1             |
|                   | +10            |
|                   | +100           |
|                   | +1000          |
|                   | +10000         |

| Socket             |                      |
|--------------------|----------------------|
| Socket 1: Enabled  |                      |
| Socket 2: Enabled  |                      |
| Socket 3: Enabled  |                      |
| Socket 4: Enabled  |                      |
| Adapter Statistics | Reset Clean Count    |
|                    | Clean Count          |
|                    | Clean Alert: 3500    |
|                    | No: 22113204         |
|                    | Mfg: 09/23/02        |
|                    | Actuations:1055      |
|                    | Adptr. Life: 10000   |
|                    | Insertions: 4220     |
|                    | Pass: 4202           |
|                    | Fail: 16             |
|                    | Yld: 99.5            |
|                    | Socket 1             |
|                    | Insertions: 1055     |
|                    | Pass: 1053           |
|                    | Fail: 2              |
|                    | Yield: 99.8          |
|                    | Socket 2 [same as 1] |
|                    | Socket 3 [same as 1] |
|                    | Socket 4 [same as 1] |

To change the Pass Limit:

1. **Select Job.**
2. **Select Remaining Devices.**
3. **Scroll to and Select an increment for adjustment.**
4. **Press the Up or Down Arrow buttons as necessary.**
5. **Press Menu. Repeat steps if needed for another increment. ■**





# Supervisor Menus

| Main Menu          |
|--------------------|
| Job                |
| Advance Pocket     |
| Align Pocket       |
| Purge              |
| Socket             |
| Home               |
| Operation*         |
| System*            |
| Robot Diagnostics^ |
| Programmer Diags^  |
| Event Log^         |

\* See next page  
^ Next odd page

- HOME sends the PNP Head to the Home position.
- Light gray shaded fields cannot be changed.

| Job     |   |
|---------|---|
| View    | Job Name<br>Device:<br>Checksum: 3FC00000<br>Mfg: INTEL<br>Adapter: PA-G021<br>Prec: 621-0086-005<br>Act: 644-0016-001  |
| Results | Passed: 992<br>Failed: 4<br>System Yld: 98.7<br>Prgrmr Yld: 99.6<br>Handler Yld: 99.5<br>Parts/Hour: 255<br>MCBI: 201<br>Skt 1 Yld: 99.9<br>Skt 2 Yld: 100<br>etc.<br>Skt Cycles: 249 |

| Job               | cont.   |
|-------------------|---|
| End               |   |
| Select            | ▶ Job 1<br>● Job 2<br>End of List                           |
| Remaining Devices | Remaining: 151<br>+-1<br>+-10<br>+-100<br>+-1000<br>+-10000 |

View the Supervisor Menus by inserting a PC card with supervisor authority.  
(The Supervisor menus are also on the next three pages.)

**Supervisor (Administrator) authorization is set in TaskLink. For more information, refer to TaskLink Help.**

**Version 05.17.00.C menus shown.**



## Supervisor Menus, continued

| Socket             |                      |
|--------------------|----------------------|
| Socket 1: Enabled  |                      |
| Socket 2: Enabled  |                      |
| Socket 3: Enabled  |                      |
| Socket 4: Enabled  |                      |
| Adapter Statistics | Reset Clean Count    |
|                    | Clean Count          |
|                    | Clean Alert: 3500    |
|                    | No: 22113204         |
|                    | Mfg: 09/23/02        |
|                    | Actuations: 1055     |
|                    | Adptr. Life: 10000   |
|                    | Insertions: 4220     |
|                    | Pass: 4202           |
|                    | Fail: 16             |
|                    | Yld: 99.5            |
|                    | Socket 1             |
|                    | Insertions: 1055     |
|                    | Pass: 1053           |
|                    | Fail: 2              |
|                    | Yield: 99.8          |
|                    | Socket 2 [Same as 1] |
|                    | Socket 3 [Same as 1] |
|                    | Socket 4 [Same as 1] |

A (•) indicates the currently selected item.

A (▶) indicates the current cursor position.

Refer to the previous page for the main menu.

***NOTE: Many of the values shown, such as the Teach and Network menus, are for example only.***





## Supervisor Menus, continued

| Operation |   |
|-----------|---|
| Job       | Pick Retries: 2<br>Error Retries: 3<br>Pocket Pitch: 4<br>Pocket Advance: 3   |
| Head      | Velocity: 250<br>Accel: 700   |
| Probes    | Puff: 50<br>Pick: 200<br>Place: 100<br>Travel: 250                            |
| Teach     | Tape: 40.0<br>Skt 1: -26.85<br>Reject: -166<br>Belt: -180<br>Restore Defaults |

- Light gray shaded fields cannot be changed.

| System          |   |
|-----------------|---|
| Time            | Hour: 4<br>Minute: 55<br>Month: 9<br>Day: 23<br>Year: 2002  |
| Odometer        | Hours: 469.92   |
|                 | Devices: 24742  |
|                 | Timekeeping: OFF  |
|                 | Erase: 0.0s<br>Blankcheck: 0.0s<br>Program: 0.0s<br>Verify: 0.0s  |
| Update Software |   |
| Network         | Network Parm:Card<br>Status: Enabled<br>PGM: FredsRR2<br>IP: 888.888.88.888<br>Prog Port: 7596<br>SUB: 255.255.248<br>GTW: 139.138.16.1<br>SNS: 0.0.0.0 |

| System                   |  |
|--------------------------|--|
| Network (cont.)          | SNS Port: 7500<br><br>HST: rr215.nt.data-io<br>DOM: nt.data-io.com<br>DNS: 888.888.88.888<br>DTS: 888.888.88.88<br>EAddr: 0010EC002211<br>Clear NetParms |
| Configuration            | Firmware Version   |
|                          | Ver 05.17.00.C   |
|                          | Installed Boards   |
|                          | Bkpln Brd Id: 2  |
|                          | Cntrl Brd Id: 1  |
|                          | Wvfrm Brd Id: 1  |
|                          | Adptr Brd Id: 3  |
| Hardware Config          |  |
| HwCfgIds 1, 3, 4         |  |
| Model: <i>name</i> (-uC) |  |
| Feeder Comm:SBelt/FFI    |  |

To change languages press Menu while pressing the Select button. Arrow Down to the desired language and press Menu twice.

Refer to the main Supervisor Menu for orientation (2 pages back).

***NOTE: Programmer Diags are only available with a Diagnostic Adapter Board.***



## Supervisor Menus, continued

| Robot Diags   |                               |
|---------------|-------------------------------|
| Robot:        | Enabled                       |
| Run Mode:     | Job/Dry Run                   |
| Belt          | Move:Fwd/Bkw                  |
|               | Pick Sensor: 0                |
|               | Speed: 400 ± 10               |
|               | Measure Device Offset: 0.00   |
| Sensors       | Tape Sprocket: 0              |
|               | Tape Broken: 0                |
|               | Reject Full: 0                |
|               | Reject Bin: 1                 |
|               | Air: 1                        |
|               | Interlock: 0                  |
|               | E-Stop: 0                     |
|               | +Overtravel: 0                |
| Socket        | State: Up                     |
|               | Actuate: 0                    |
|               | Act.Duration:150 <sup>1</sup> |
| Probe 1- 4    | Position: Up                  |
|               | Vacuum: Enabled               |
|               | Puff: Enabled                 |
|               | Vac Sense: 1                  |
|               | Speed: 135 ± 5                |
| Head Position | Head: 0                       |

| Programmer         | Diags   |
|--------------------|---|
| Programr: Enabled  |   |
| Exercise Display   |   |
| Test Cycles: 3     |   |
| Test All: PASS     | Programmer Diagnostic tests require a Diagnostic Adapter Board for all items below this line. |
| Bus Test: PASS     |   |
| Adtr ID Test: PASS |   |
| LED Dvr Test: PASS |   |
| G Node Test: PASS  |   |
| Vcc OC Test: PASS  |   |
| Vpp OC Test: PASS  |   |
| I2C Bus Test: PASS |   |
| DAC Ref Test: PASS |   |
| GSlew Test: PASS   |   |
| High RAM Test:     |   |
| Continuity Loop: 3 |   |

| Event Log |  |
|-----------|--|
| View      |  |
| Clear     |  |

• Light gray shaded fields cannot be changed.

<sup>1</sup> Socket Actuation duration is set by the Socket Adapter in some instances.

For more information about menu commands, see Chapter 3 of the ProLINE-RoadRunner Owner's Manual. ■





## Warnings and Cautions



**Compressed Air**

Point air hoses away from body. Always wear approved eye protection.



**Loud Noise**

Sound pressure levels may exceed 85 db. Hearing protection is recommended for prolonged exposure at this level.



**High Voltage**

Turn power off before removing electronics cover.



**Heavy Object**

This equipment weighs approximately 15 – 17 kg (33 – 38 lbs). Do not drop. Mount only with approved hardware.



**Moving Parts**

Pinch warning. Keep hands away from moving parts.



**Electrostatic Discharge**

Electrostatic Discharge (ESD) may cause damage. Discharge static against a common ground.





**Chapter 2**



# Installation

**Mounting onto the  
Feeder Table ..... 16**

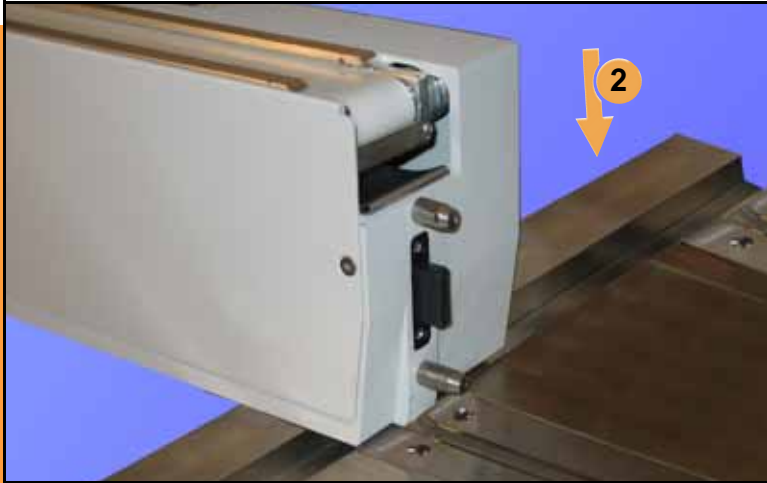
**Connecting Power and Air ..... 18**

**Switching the Power On ..... 20**





## Mounting onto the Feeder Table



To mount RoadRunner onto a Feeder Table:

1. Hold RoadRunner, one hand in the handhold and one under the Conveyor, so the Conveyor overlaps the Feeder Table by 40 mm and is above a slot.

***NOTE: Do not use the four leftmost slots on the table or the two rightmost slots.***

2. Lower RoadRunner allowing the nose to rest on the Feeder Table. Ensure that it settles into a slot.




**Warning:**




Heavy. 17 kg (37 lb). Do not drop.  
Mount only on approved units.



3. Still holding the handhold, slide RoadRunner forward as far as it will go. RoadRunner locks into place. ■

 **Warning**

 Heavy. 17 kg. Do not drop. Turn off RoadRunner and disconnect facilities before removing it from a feeder table.





## Connecting Power and Air



To connect the power and the air:

1. Turn the RoadRunner power switch to the Off (0) position.
2. Grasp the air hose *behind* the “quick connect” collar and push it firmly onto the male fitting. The collar must be allowed to move back as it goes onto the fitting.

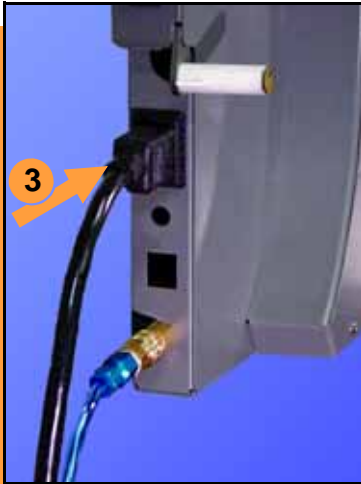
**NOTE:** Compressed air must be clean and dry at approximately 5.25 kgf/cm<sup>2</sup> (75 psi).



### Warning:



Point air hoses away from body.  
Wear approved eye protection.



3. Connect to a grounded power source using a cable with a standard IEC 320 plug. RoadRunner accepts power between 100 and 240 VAC, 50/60Hz.

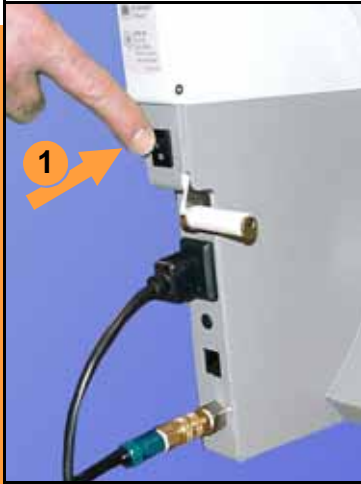
*NOTE: To disconnect the air hose, grasp the collar on the connector and pull back.*

*The air line is equipped with a "quick connect" that will stop airflow when disconnected. ■*





## Switching the Power On



To switch the power on:

1. Push the power rocker switch to On (I).

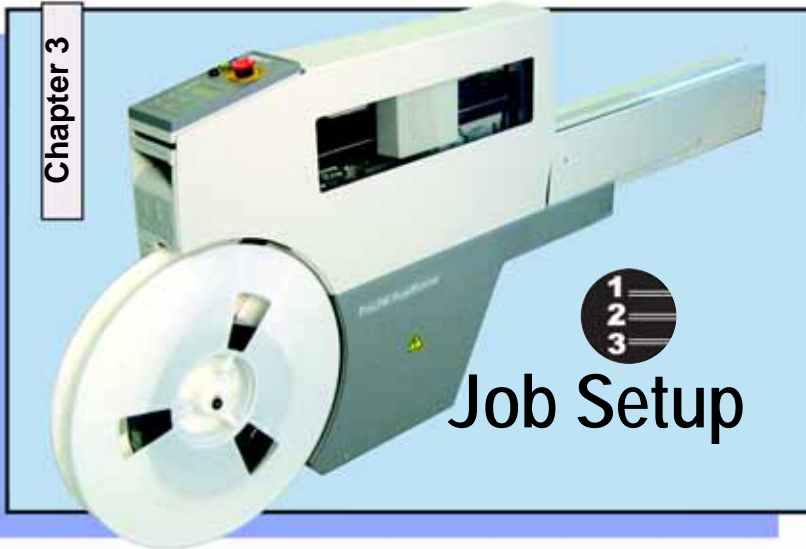
All the Control Panel indicator lamps light up. A Self-test runs. Then only the blue lamp will remain on and the version number will display.

If all the indicator lamps start blinking, a serious error has occurred. Turn the unit off then on again. If the error continues, have the unit serviced.

2. If no errors display, RoadRunner is operation ready. ■



## Chapter 3



**Inserting a Job Card ..... 22**

**Changing the Precisor ..... 24**

**Changing the  
Actuator Plate..... 26**

**Changing the  
Socket Adapter..... 28**

**Adjusting the Tape-In Module ..... 30**

**Loading a Reel of Devices ..... 32**

**Aligning the Tape Pockets ..... 34**



## Inserting a Job Card



To run a job, insert a TaskLink job card into the PC card slot. Use only TYPE I or TYPE II PC cards (PCMCIA).

To insert a job card:

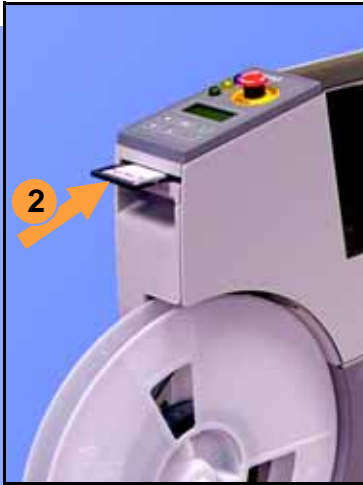
1. If the power switch is on, make sure the blue lamp is lit.



### Caution:

Electrostatic discharge may cause damage. Discharge static against common ground prior to inserting job card.





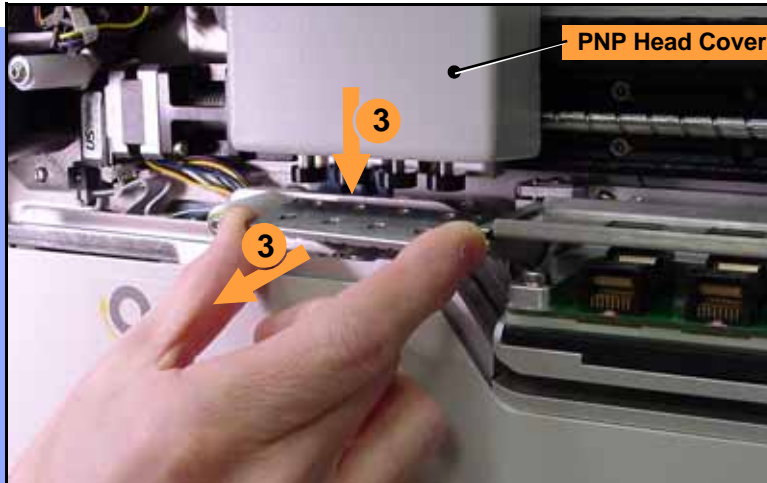
2. Slide the job card into the PC card slot.

*NOTE: When fully inserted, the job card extends slightly from the PCcard slot.*

*NOTE: Do not eject the card unless the blue lamp is lit (or the power is off).*

3. The Card Eject button can be pushed to remove the card when the blue lamp is lit. ■

## Changing the Precisor



To change the precisor:

1. Select Job, then End, wait for the blue lamp to light and turn the power Off (0).
2. Lift off the Robotics Cover.
3. Starting at one end, pull the precisor down off the magnet.

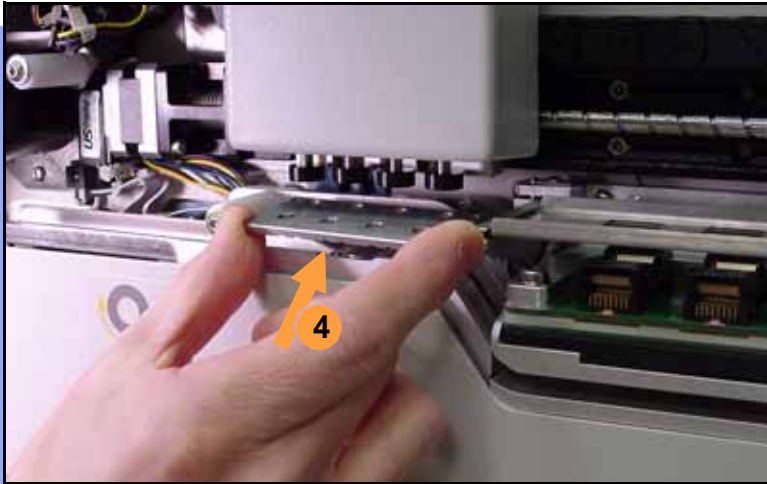
The PNP Head Cover can be removed for easier access (pull straight out.)



**Warning:**



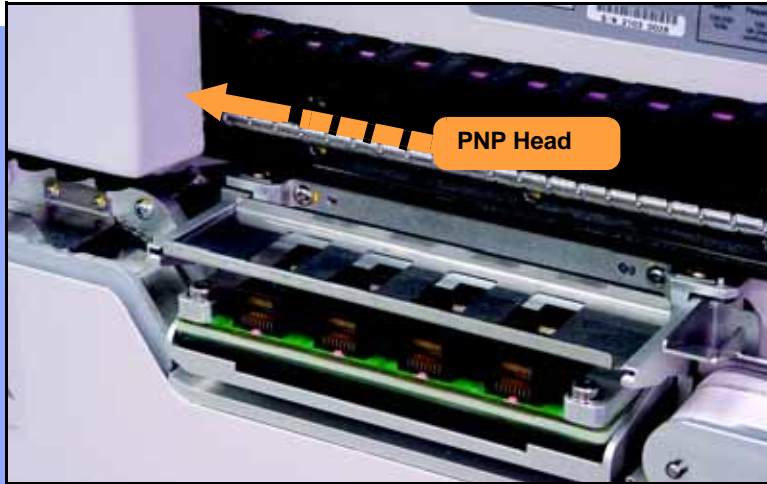
Pinch Warning. Keep hands away from moving parts.



4. When inserting the new precisor, make sure that the part number faces up and that the small holes near the precisor edge fit over the dowel pins on the PNP head.

There should be no visible gap between the precisor and the head. ■

## Changing the Actuator Plate



To change the Actuator Plate:

1. Select Job, then End, wait for the blue lamp to light and turn the power Off (0).
2. Lift off the Robotics Cover.

Once power is off, the PNP Head can be moved by hand to allow access to the Actuator Plate.



### Warning:



Pinch Warning. Keep hands away from moving parts.

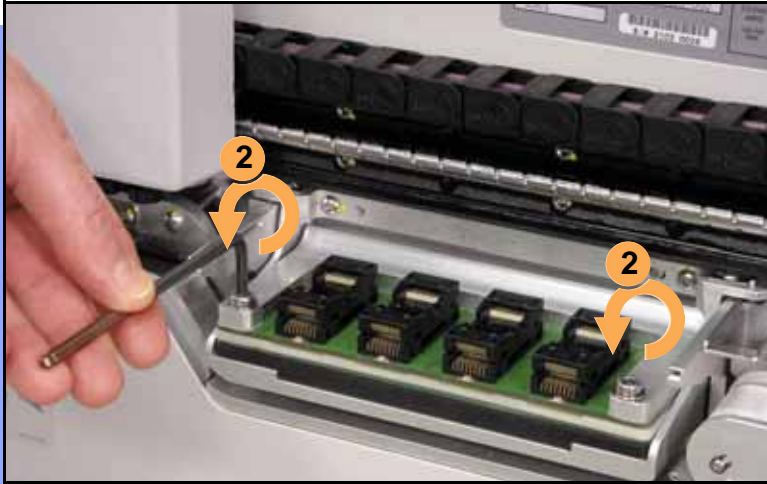


3. Pull the Actuator Plate to slide it out of the grooved brackets.

***NOTE: The Actuator Plate must be out to access or change the Socket Adapter.***

To change the Socket Adapter, see the procedure on the following page. ■

## Changing the Socket Adapter



To change the Socket Adapter (with the Actuator Plate removed):

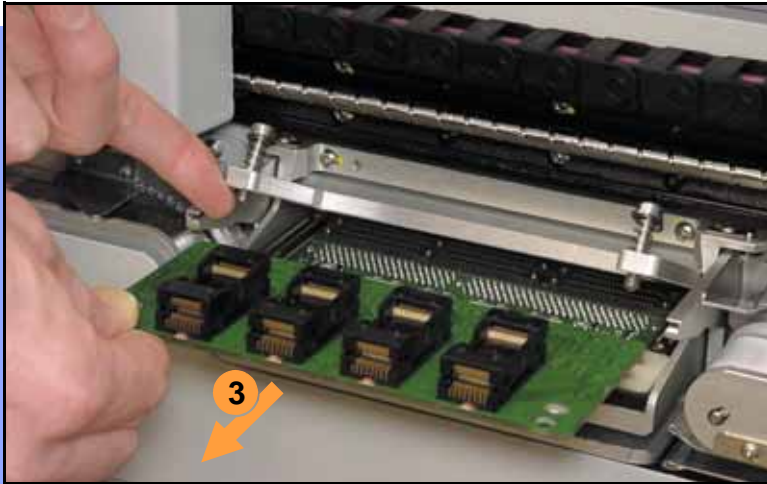
1. Make sure the power is Off (0).
2. Unscrew the two captive screws and lift the adapter bracket.



### Caution:



Electrostatic Discharge may cause damage.  
Discharge static against common ground.

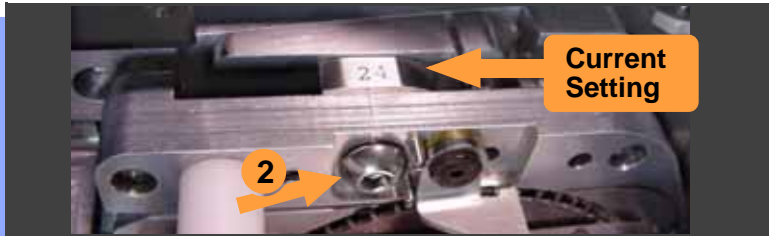


3. Without touching the gold contact surfaces on the bottom of the adapter, lift the adapter free.
4. Insert the correct adapter, making sure that it seats on the dowel pins.

*NOTE: Each type of device may have its own Socket Adapter.*

5. Tighten the screws and replace the Actuator Plate. ■

## Adjusting the Tape-In Module

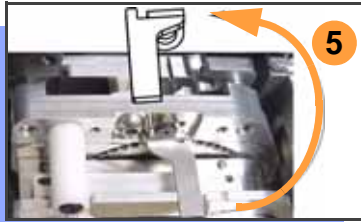
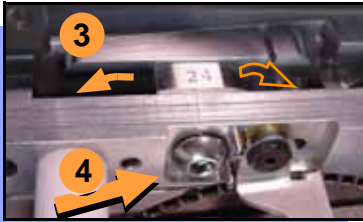


If you have an Adjustable Tape-In Module, you may need to adjust the tape width.

Adjustable Tape-In Module only—  
If the etched number on the 3-Position Spacer does not match your tape width dimension (mm) then adjust it:

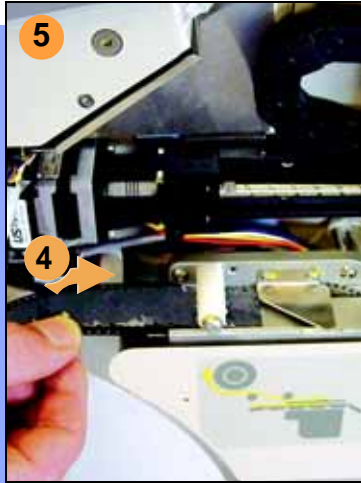
1. With the power off (0), push the PNP head out of the way.
2. Loosen the Position Locking Screw most of the way out using a 4 mm Allen wrench.





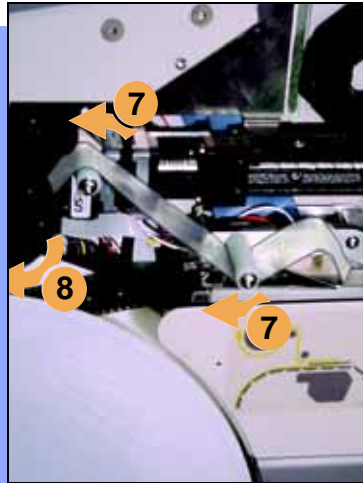
3. Rotate the 3-Position Spacer with your finger until you read 16, 24 or 32, corresponding to your tape width.
4. Retighten the Position Locking Screw.
5. Rotate the Peel Bar counterclockwise 180 degrees to the up position.
6. Lift and move the magnetic Front Track to the position that fits your tape width.
7. Rotate the Peel Bar back down. ■

## Loading a Reel of Devices



To load and thread device tape:

1. Ensure you have the correct Tape-In Module/adjustment for your tape (tape fits in track).
2. Place a reel onto the RoadRunner spindle.
3. Lock the reel in place by rotating the brass button on the spindle end.
4. Insert the device tape into the Tape-In Module and onto the sprocket.
5. Select Advance Pocket from the Operator Menu, then press the Up Arrow button.

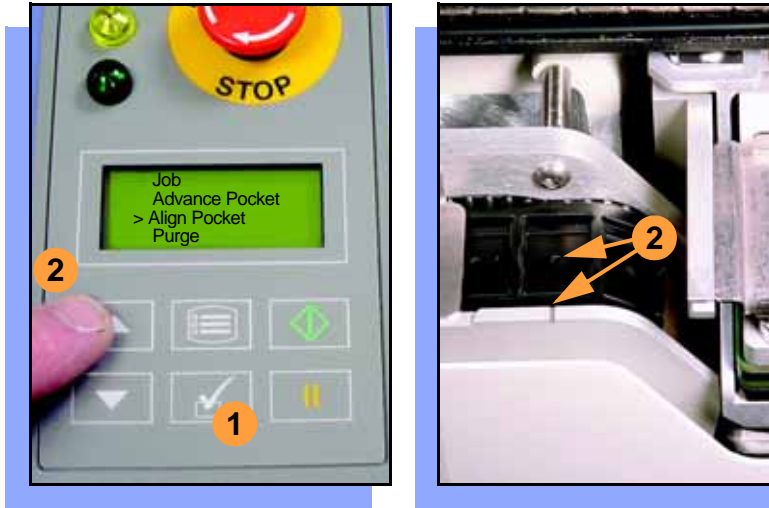


6. When the tape is advanced past the Peel Bar, separate the cover tape from the device tape.
7. Thread the cover tape up through the cover tape path and attach it to the Cover Tape Take-Up Reel. Advance the tape as necessary.

*NOTE: A small piece of adhesive tape may be needed to stick the cover tape to the Take-Up Reel.*

8. Turn the Take-Up Reel to take up slack cover tape.
9. Align the tape pockets as described in the following procedure. ■

## Aligning the Tape Pockets



To align the tape pockets:

1. Select Align Pocket from the Operator Menu.
2. Press the Up Arrow button to advance the tape until the next tape pocket center hole is approximately centered at the pick point alignment mark. *Do not* advance devices past the pick point. They may fall and jam the tape path. *Do not use the Down Arrow to align.*

***NOTE: This aligning procedure must be performed each time power is applied, such as after releasing the Emergency Stop. ■***



**Chapter 4**

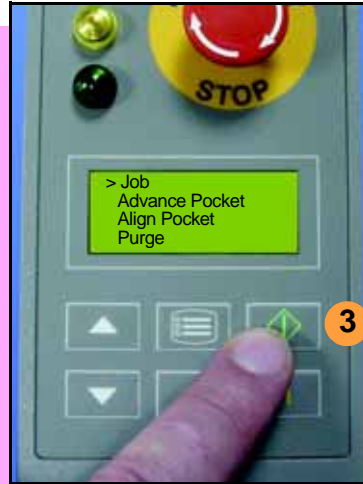
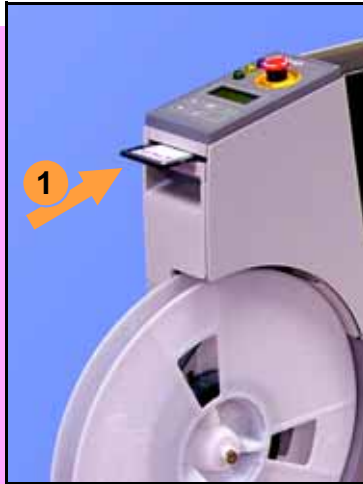


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## Running a Job



To run a job:

1. Insert a job card into the PC card slot.
2. Clear the conveyor belt of any unneeded devices.

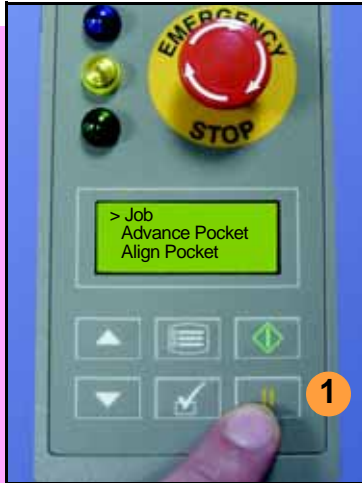
***NOTE: If the PC Card has Supervisor authority, ensure the correct job is selected. See Supervisor Menu.***

3. Press Start. The green lamp will start blinking.

When the programmed devices reach the assembly machine pick point, the belt will pause and the green lamp will stay lit without blinking. ■



## Pausing or Stopping a Job



To pause at the end of the current operation:

1. Press Pause on the control panel.

To instantly stop in an emergency situation:

2. Press the Emergency Stop (E-Stop) button.

**The E-Stop does not stop the Assembly machine. ■**



### Warning

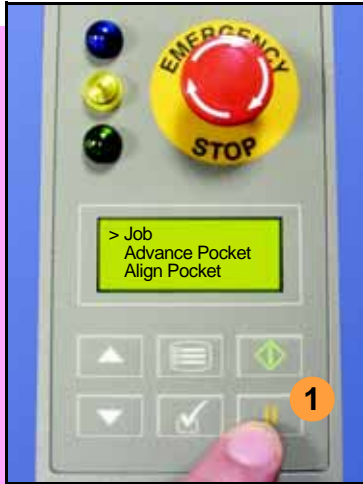


Electrical shock hazard. The E-Stop does not stop electricity to RoadRunner.





## Ending a Job



Whenever you are going to change job cards, you must first end the current job.

To end the current job:

1. Press the Pause button.
2. Select End from the Job Menu. "Job" is in the main menu.

The system will finish processing devices and place the devices on the belt, but no additional devices will get picked from the tape.





3. Clear away excess devices from the conveyor belt.
4. Empty the Reject Bin. (See next heading.)
5. Empty the Cover Tape Take-Up Reel. (See “Emptying Cover Tape” ahead several pages.) ■





## Emptying the Reject Bin




To empty the Reject Bin:

1. Press the Pause button.
2. Lift the Reject Bin straight up by the finger tab and then out.

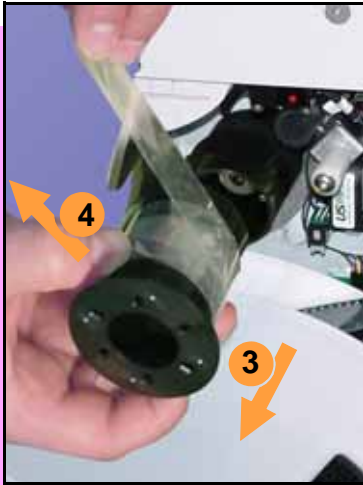
When reinserting the Reject Bin, be sure the bin is *completely* lowered so that the tab is positioned out of the path of the probes. ■

 **Warning:**

 Pinch Warning. Keep hands away from moving parts.



## Emptying Cover Tape



To empty the Cover Tape Take-Up Reel:

1. Press Pause.
2. Cut the cover tape, leaving enough slack to re-attach.
3. Pull the Take-Up Reel straight out. (Reels with slots require rotating before pulling off.)
4. Unwind the used cover tape and discard it.
5. Replace the Take-Up Reel—slide it on and rotate it to line up with the pins, and push (or twist). ■



**Warning:**

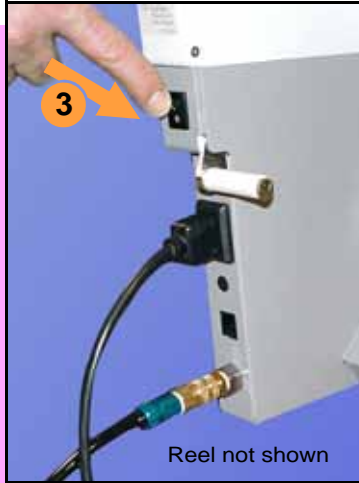
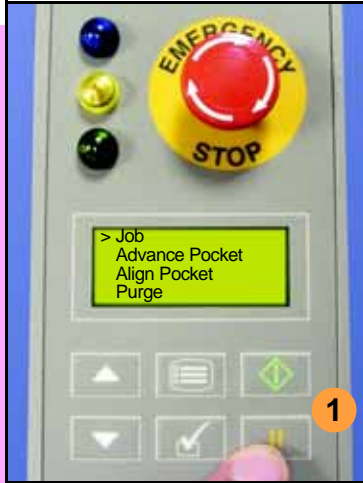


Pinch Warning. Keep hands away from moving parts.



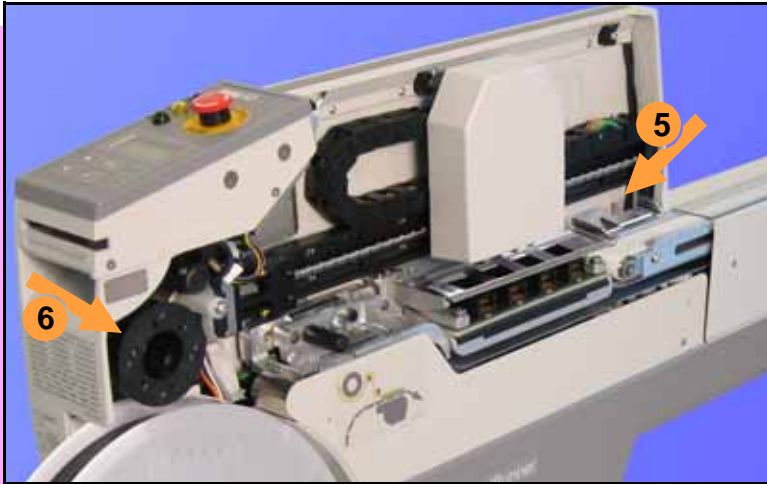


## Shutting Down



To shut down RoadRunner:

1. Press Pause.
2. Select End Job from the Job Menu and wait for all devices to be placed on the belt.
3. Switch the power Off (0).
4. Remove devices from the conveyor belt.



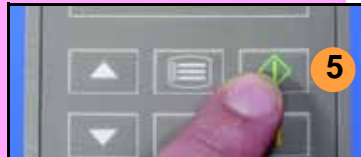
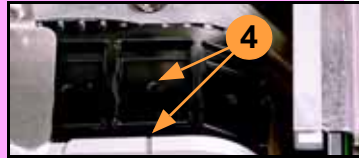
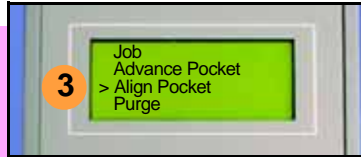
5. Empty the Reject Bin.
6. Empty the Take-Up Reel. (For more, see the previous heading.)
7. Remove the air hose, or switch off the air flow.

***NOTE:*** When disconnecting the air hose, pull the connector collar back as you pull the connector off. ■





## Restarting a Job



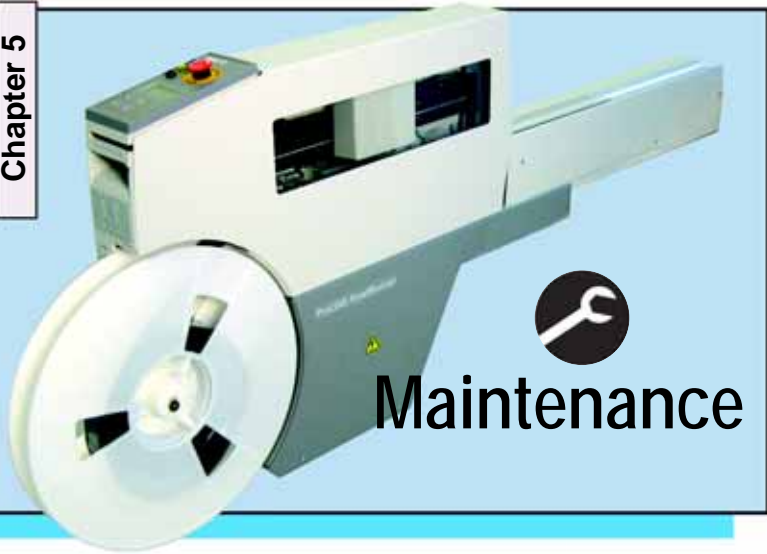
To restart RoadRunner after a pause or an emergency stop:

1. Rotate the Emergency Stop button clockwise to release it, if needed.
2. Press Menu until the main level menu is displayed
3. Select Align Pocket.
4. Press the Up Arrow to advance the device tape until the *next* pocket center hole lines up with the alignment mark.
5. Press Start.

The job will resume. ■



**Chapter 5**

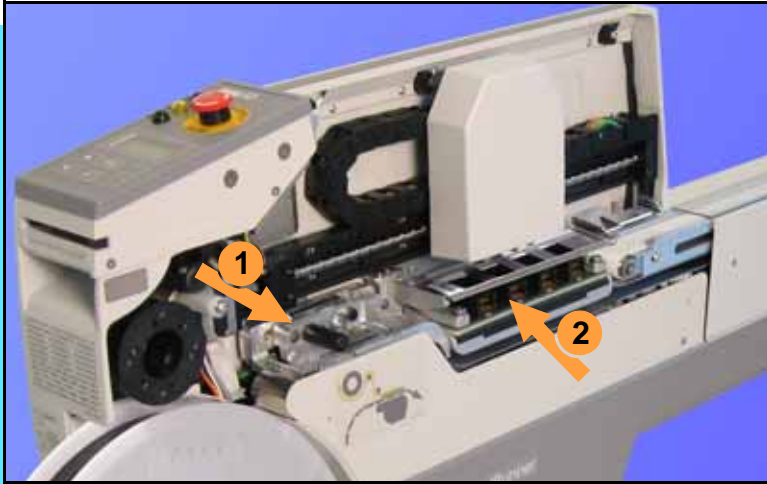


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## Cleaning with Air



To prevent dust accumulation, inject compressed air into the following component areas:

**NOTE:** Compressed air must be clean and dry. ■

1. Tape-In Module (weekly).
2. Sockets (daily). Sockets should be opened and closed by hand while air is injected.



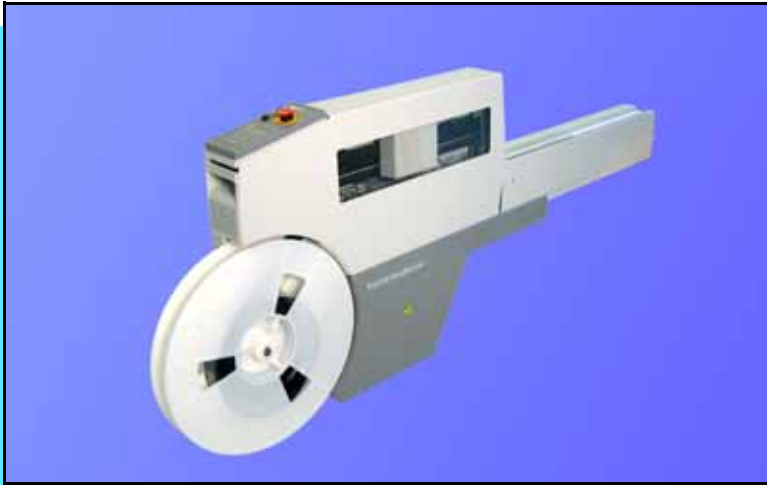
### Warning:

Point Air Hoses Away From Body.  
Wear Approved Eye Protection.





## Cleaning with Alcohol



To prevent dust and oil accumulations, clean the following component areas with isopropyl alcohol on a lint-free cloth.

- Chassis and Covers (every 3 months).
- Conveyor belt (daily). See "Device Rotation" in the Troubleshooting chapter.

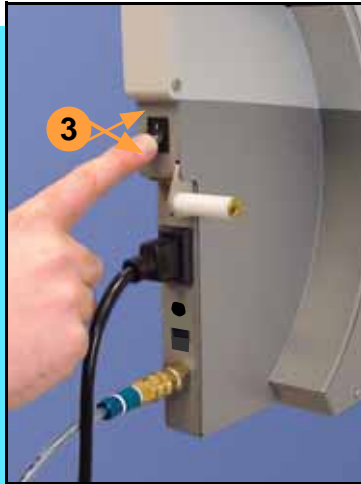
***NOTE: Dry the conveyor belt before rotating it.***

These intervals are based on running 40,000 devices weekly. ■





## Running the Self-test



Run the Self-test procedure approximately once a week.

To run the Self-test procedure:

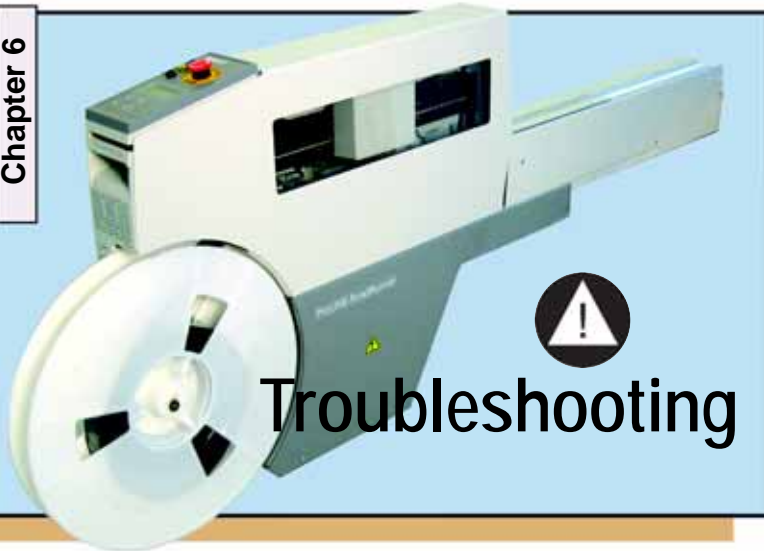
1. Press Pause.
2. Clear all devices from the sockets and from the conveyor belt.
3. Toggle the power switch off and then back on.

The Self-test will run, checking the condition of the components.

4. Check the display for system errors. ■



**Chapter 6**



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## Viewing Errors



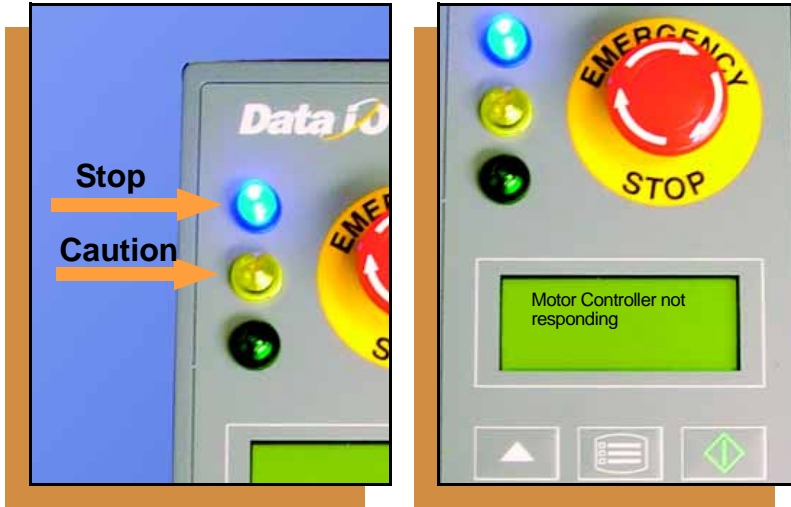
To view and correct errors:

1. Messages will appear in the keypad display.
2. Check the condition—tape path, Reject Bin, etc.—implied by the message.

If you cannot correct the error condition, contact a service technician.

3. Press Menu to remove the message.

If there are other error messages the next one will appear.



Some common error messages are listed below. For more information see “Troubleshooting” in the *ProLINE-RoadRunner Owner’s Manual*.

| Lamp Color         | Error Message                            |
|--------------------|--|
| No change in lamps | Card not present                         |
| Yellow             | Reject Bin needs to be emptied           |
| Blue               | Cover tape broken                        |
| Blue               | Emergency Stop is activated <sup>1</sup> |
| Blue               | Motor controller not responding          |

<sup>1</sup>Twist the Emergency Stop button to release it. ■





## Enabling a Socket



If a socket repeatedly becomes disabled, RoadRunner should be serviced.

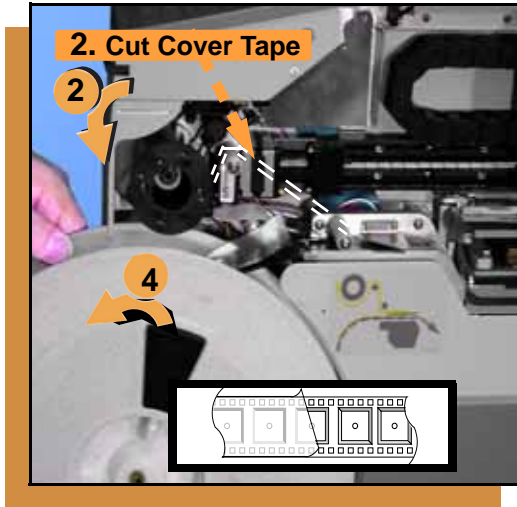
To re-enable a disabled socket:

1. Select Socket from the top level menu.
2. Arrow down and select the disabled socket from the Socket menu. (A dot appears.)
3. Press the Up Arrow button to re-enable the socket.

**NOTE:** To disable a probe, disable the probe's corresponding socket. ■



## Clearing Jammed Tape



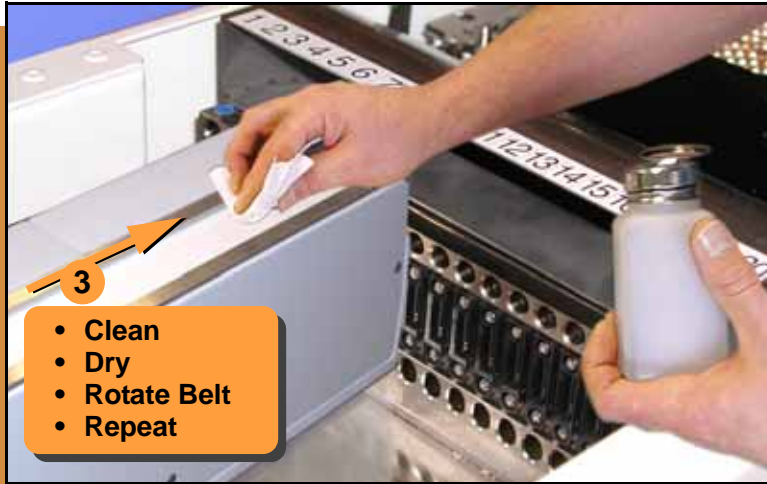
If the tape jams, an error message displays and the blue lamp illuminates. To clear the tape path:

1. Press the Emergency Stop button (to continue the job later) or select Job, then End. Then switch the power off.
2. Unroll one turn of cover tape and cut it near the Take-Up Reel.
3. Cut the device tape where it exits the conveyor.
4. At the tape reel, pull the tape out backwards until the end is free from the tape path.
5. Trim away any flaws before reloading. ■





## Device Rotation



If devices rotate excessively on the conveyor belt:

1. Press Pause. Wait for all the devices to get picked from the belt.
2. Press the Emergency Stop.
3. Remove the Dust Cover and clean only the exposed surface of the conveyor belt with isopropyl alcohol on a lint-free cloth, *then dry it*. Rotate the belt by hand and repeat until clean.
4. To continue, replace the Conveyor Dust Cover, and release the Emergency Stop button. Align the tape pockets (Chapter 3), then press Start. ■





## Technical Support

Contact your local Data I/O representative.

To find your local representative, go to  
<http://www.dataio.com/contact/repsearch.asp>



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